

Constraining the environment of compact binary mergers with self-lensing signatures

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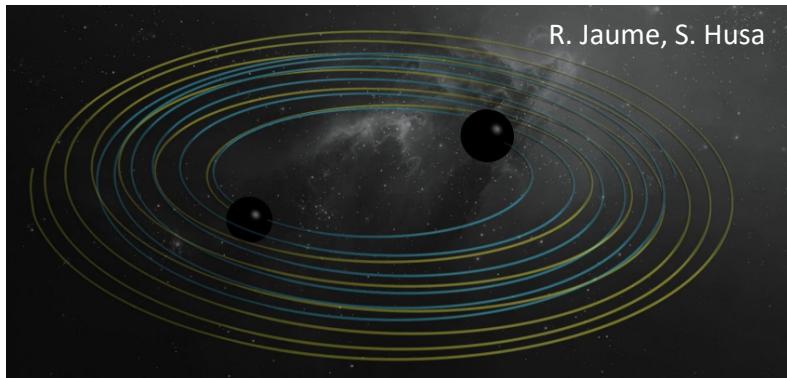


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EXCELENCIA
MARÍA
DE MAEZTU
2020-2024

Motivation

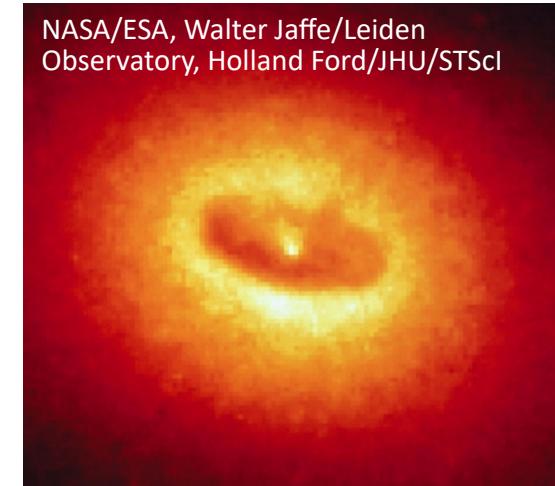
Gravitational waves from different environments:



Isolated binaries, «in the field»



Binaries in star clusters



Binaries in AGN disks

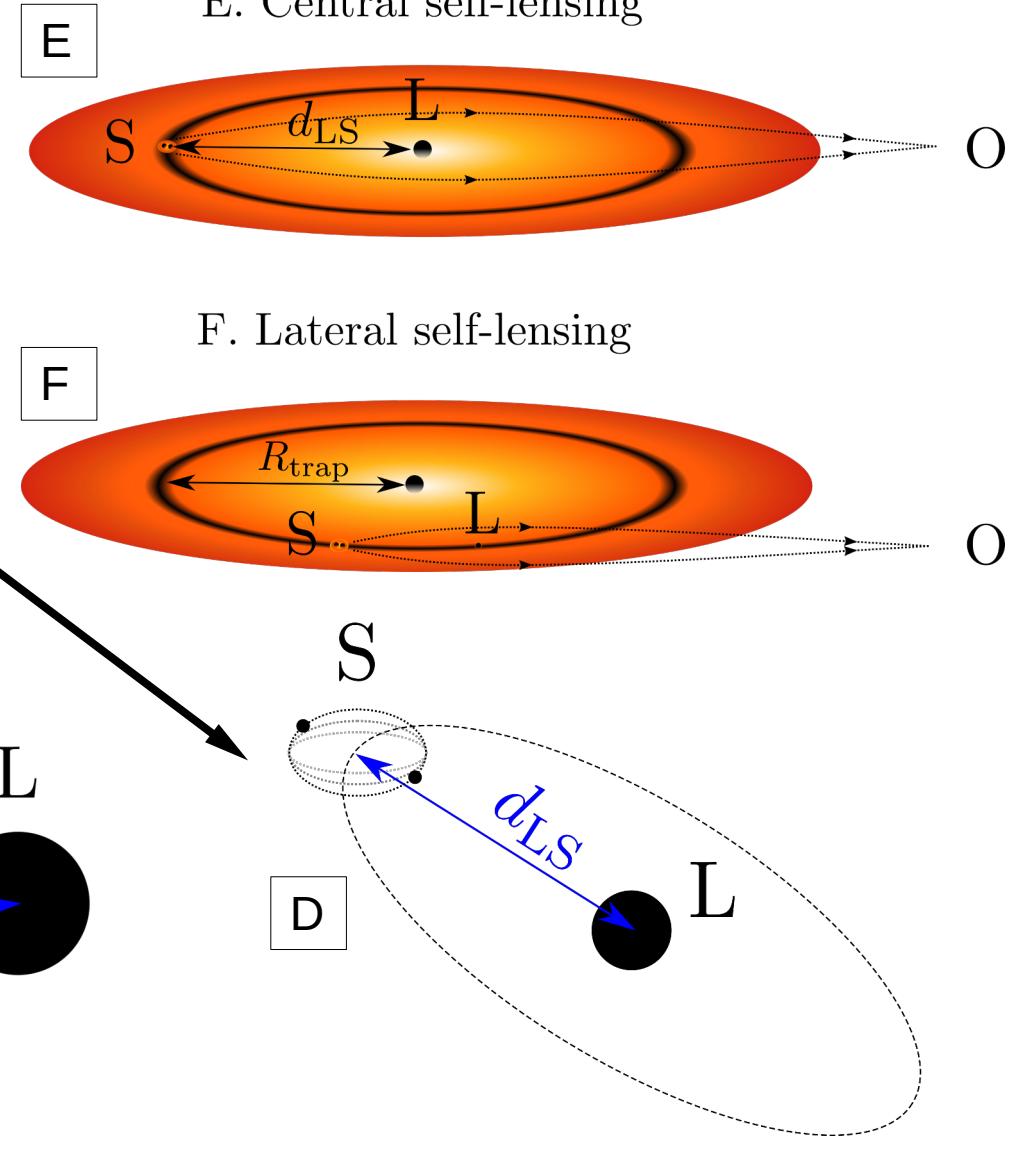
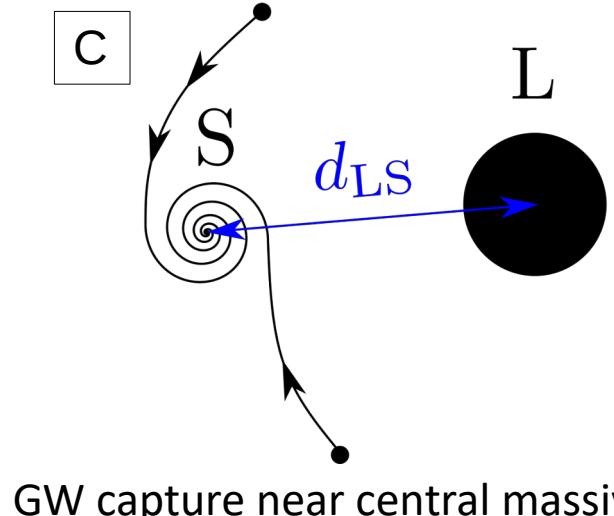
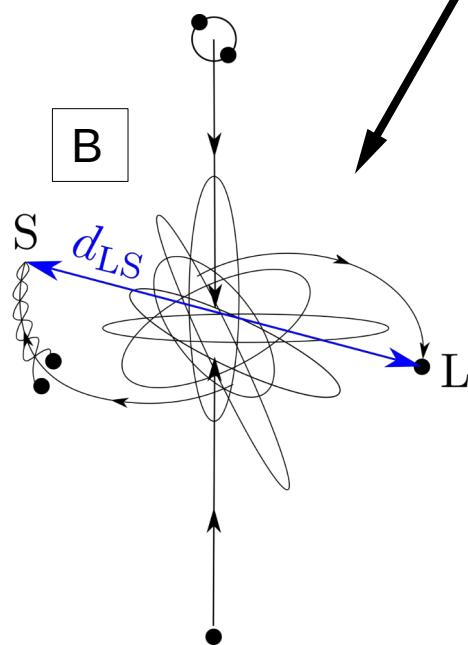
How to distinguish the environment of GW sources?

Spins, eccentricity, Doppler shifts... + self-lensing

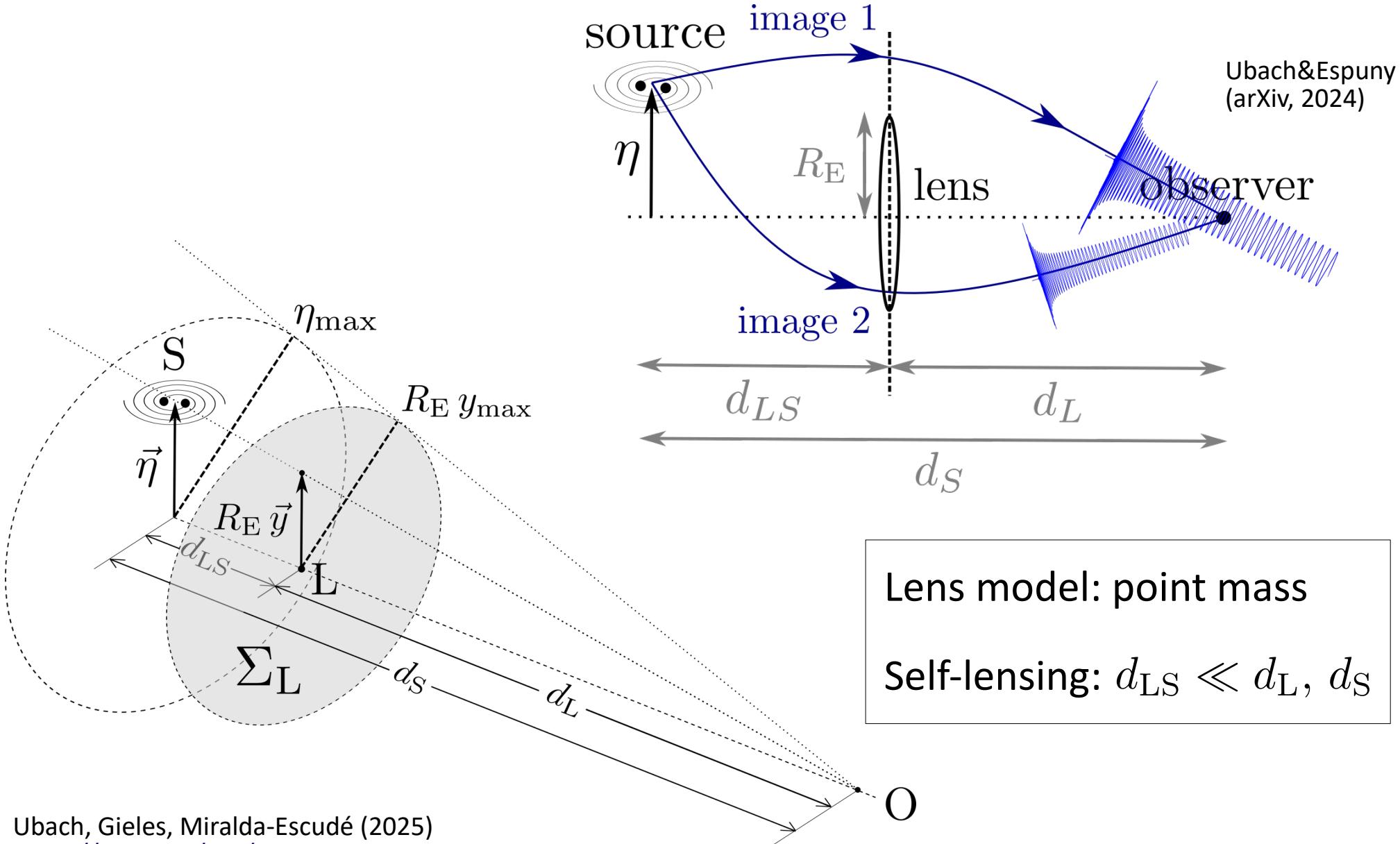
Environments and scenarios

Star (globular/nuclear) cluster

A
General optical depth for the detectable BH population



Gravitational lensing



Probability of self-lensing

- Probability \simeq optical depth τ

$$\tau \propto \frac{\sigma^2}{c^2}$$

$$\tau \propto \frac{v_{\text{orbit}}^2}{c^2} \propto \frac{R_L}{d_{\text{LS}}} \xrightarrow{\frac{2Gm_L}{c^2}}$$

population of lenses,
optical lensing one lens, e.g. Gould (1995)

→ low value: self-lensing usually neglected

Nevertheless,

- very dense (relativistic) environments, $\sigma \uparrow$
- # detections $\uparrow\uparrow$ (next generation detectors)
→ low probability \neq impossible

Detectability

Probability of detectable lensing

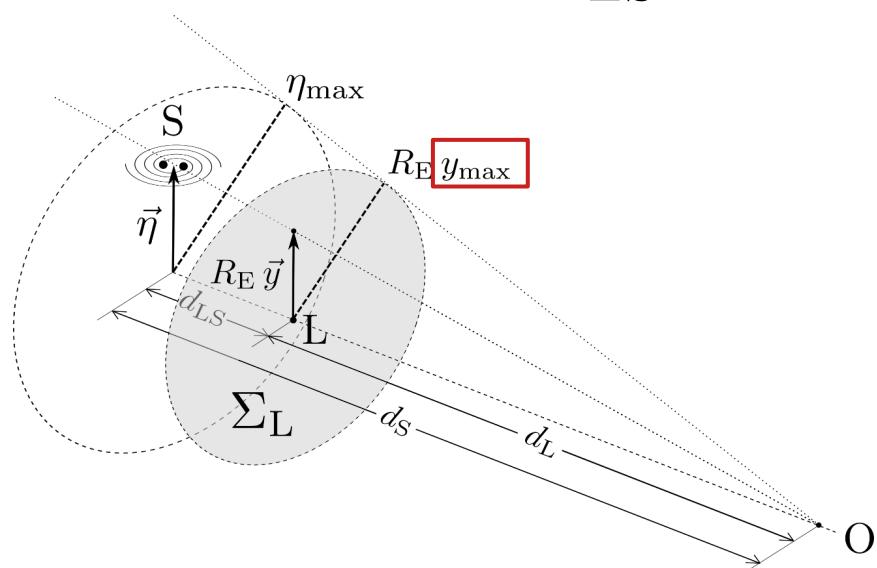
Detectability:

- Distortion (diffraction, interference)
- Multiple images

$$\tau \propto \frac{\sigma^2}{c^2} \boxed{y_{\max}^2}$$

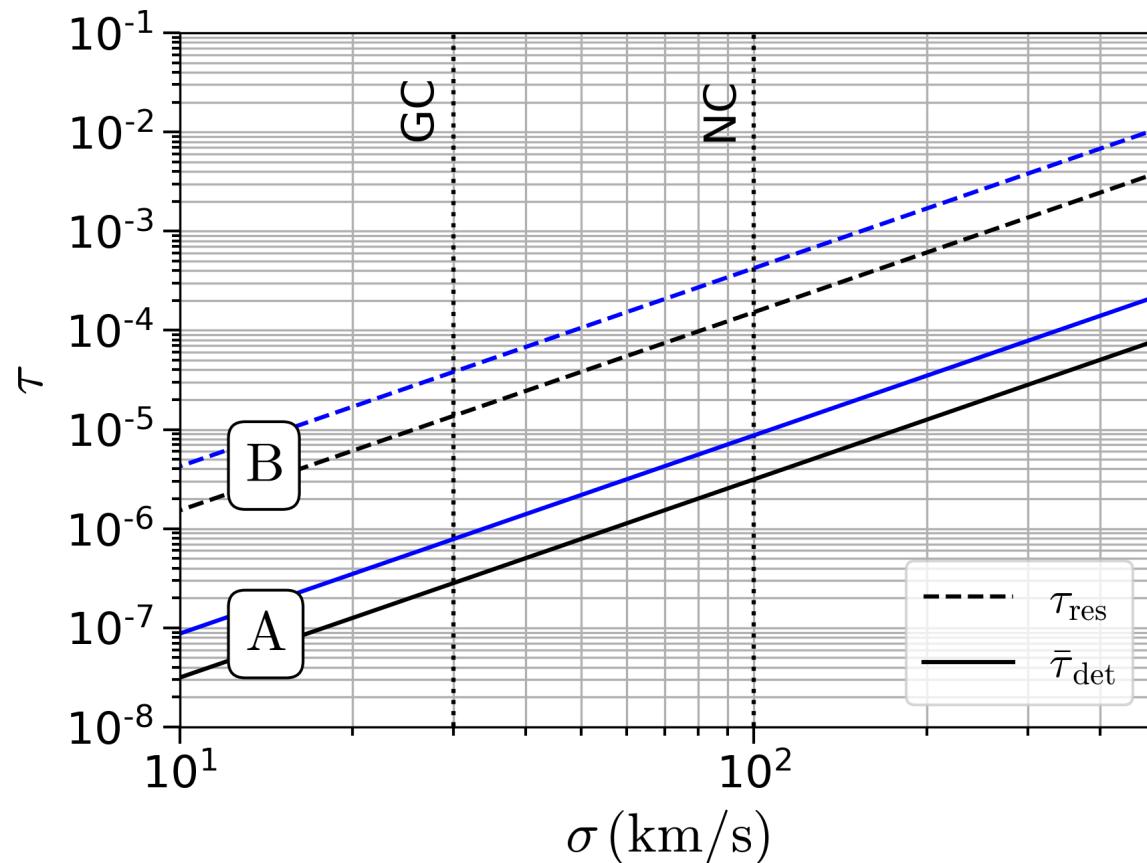
+ considering
just detectable
lens population

$$\tau \propto \frac{v_{\text{orbit}}^2}{c^2} \boxed{y_{\max}^2} \propto \frac{R_L}{d_{LS}} \boxed{y_{\max}^2}$$



Probability of self-lensing

- Probability of self-lensing (population): $\tau \propto \frac{\sigma^2}{c^2} y_{\max}^2$



$y_{\max} \uparrow$ when SNR \uparrow

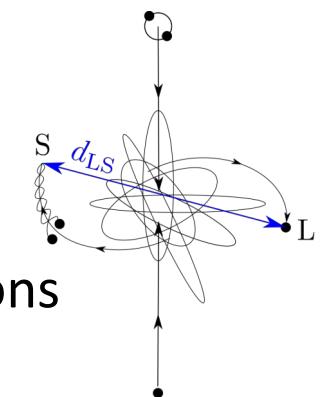
$$y_{\max} = 2.5$$
$$y_{\max} = 1.5$$

B

Resonant interactions

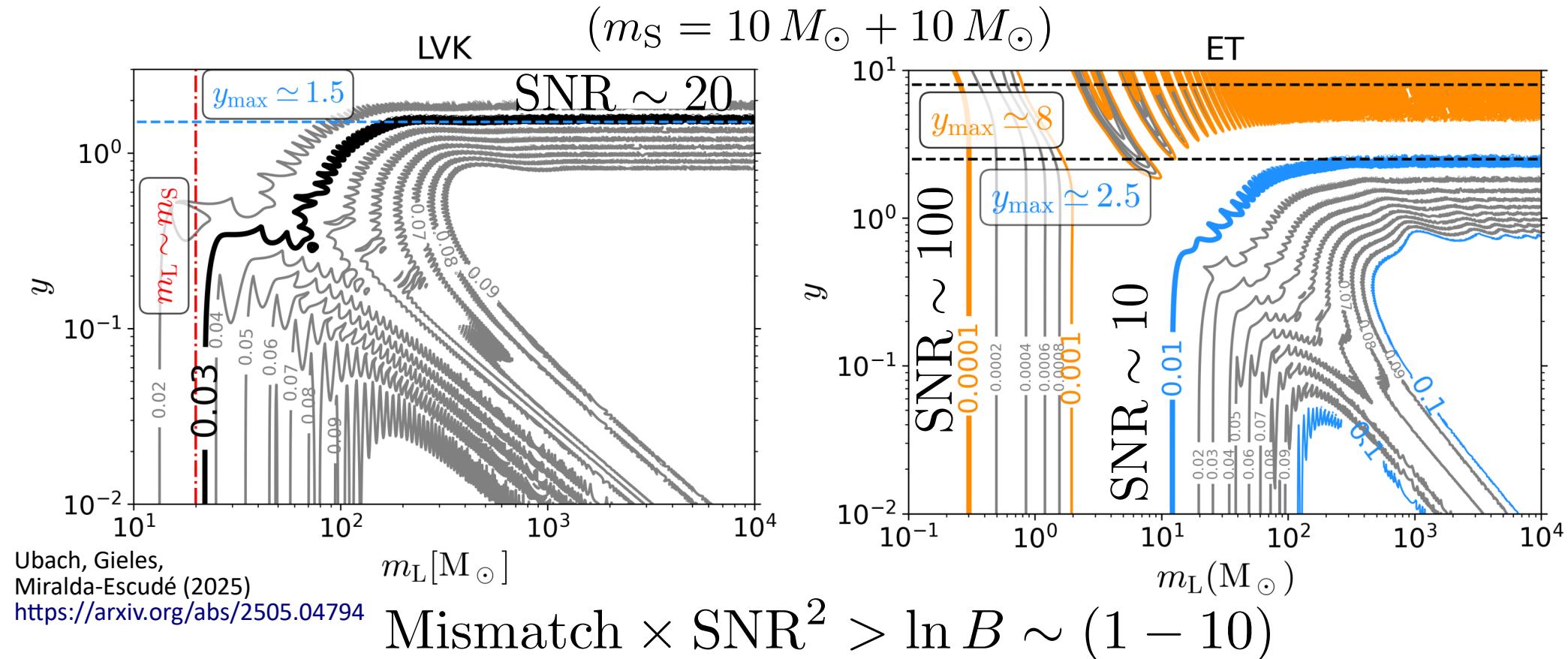
A

General optical depth
for the detectable BH
population



Detectability

- Distortion on single waveform (diffraction, interference)

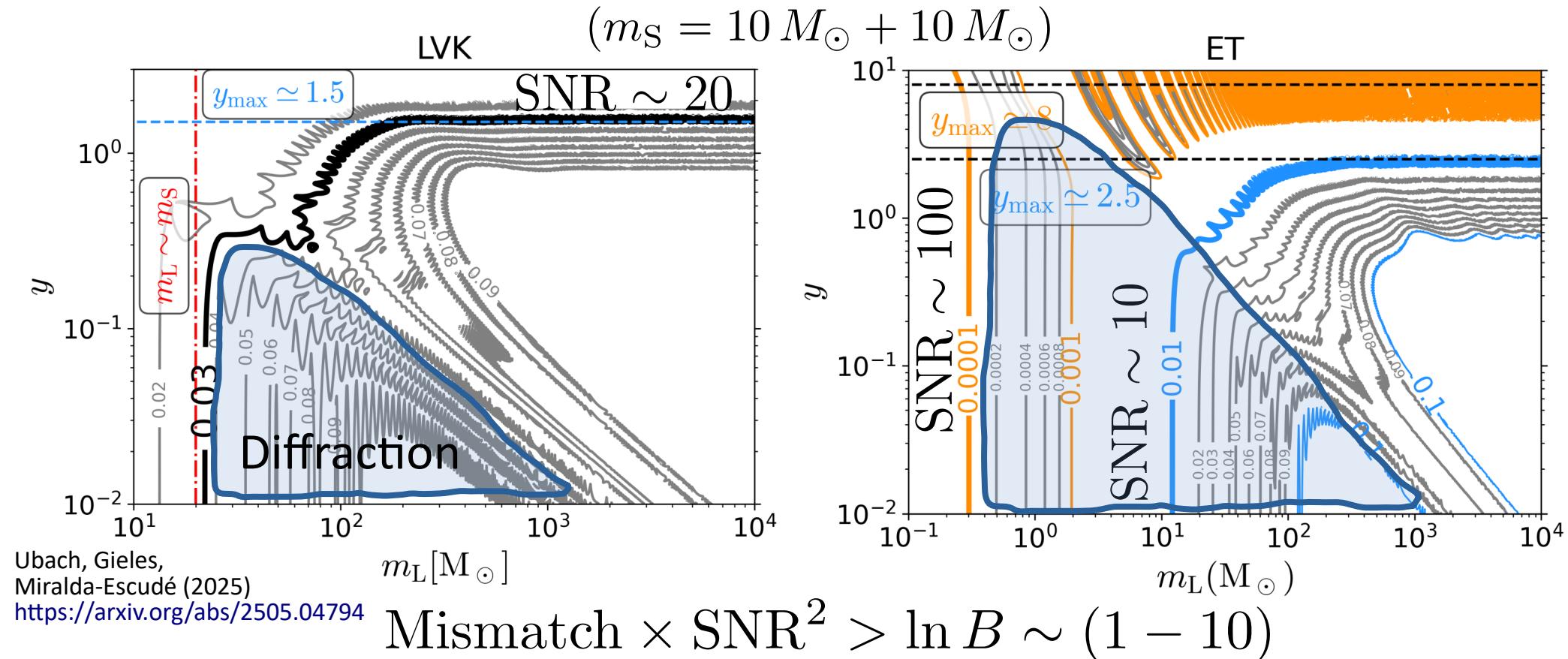


$$\begin{cases} m_L \gtrsim m_S \\ y < y_{\max} \simeq 1.5 \end{cases}$$

$$y < y_{\max} \simeq 2.5$$

Detectability

- Distortion on single waveform (diffraction, interference)

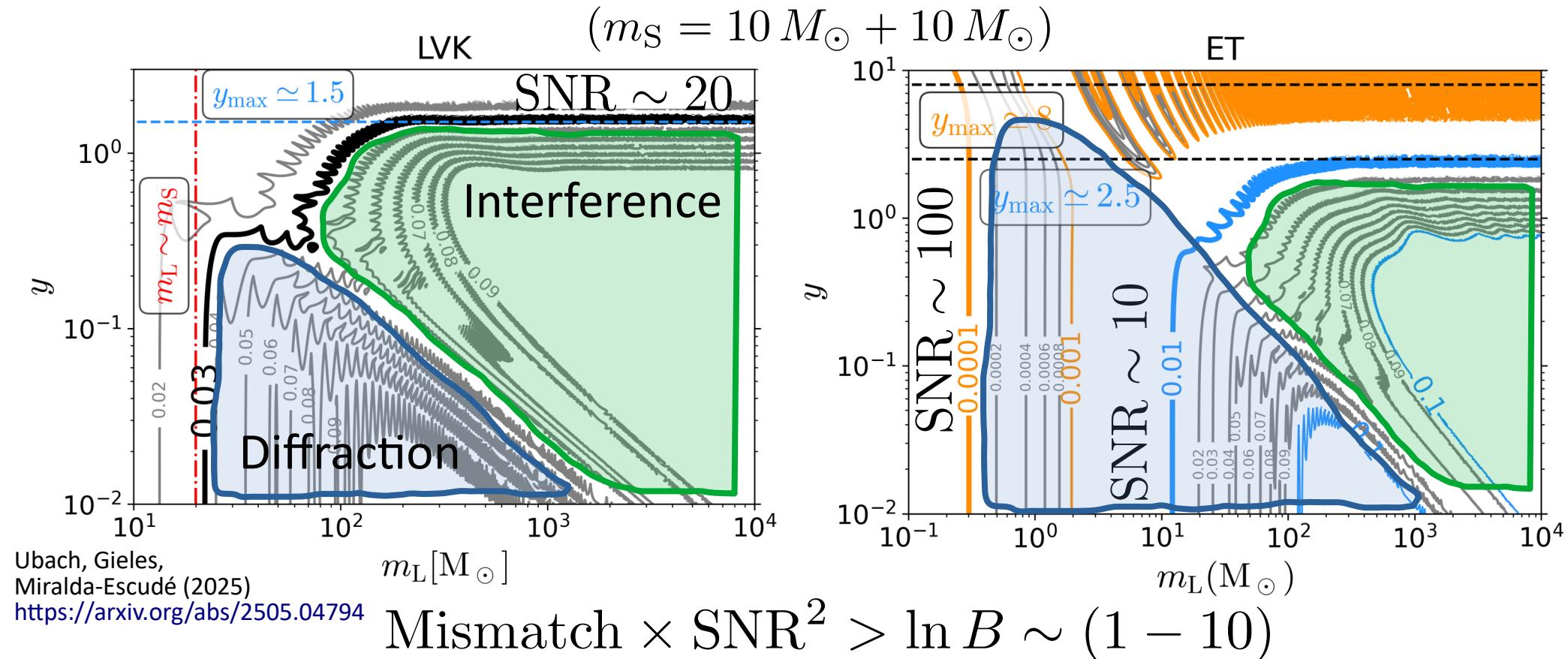


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Detectability

- Distortion on single waveform (diffraction, interference)

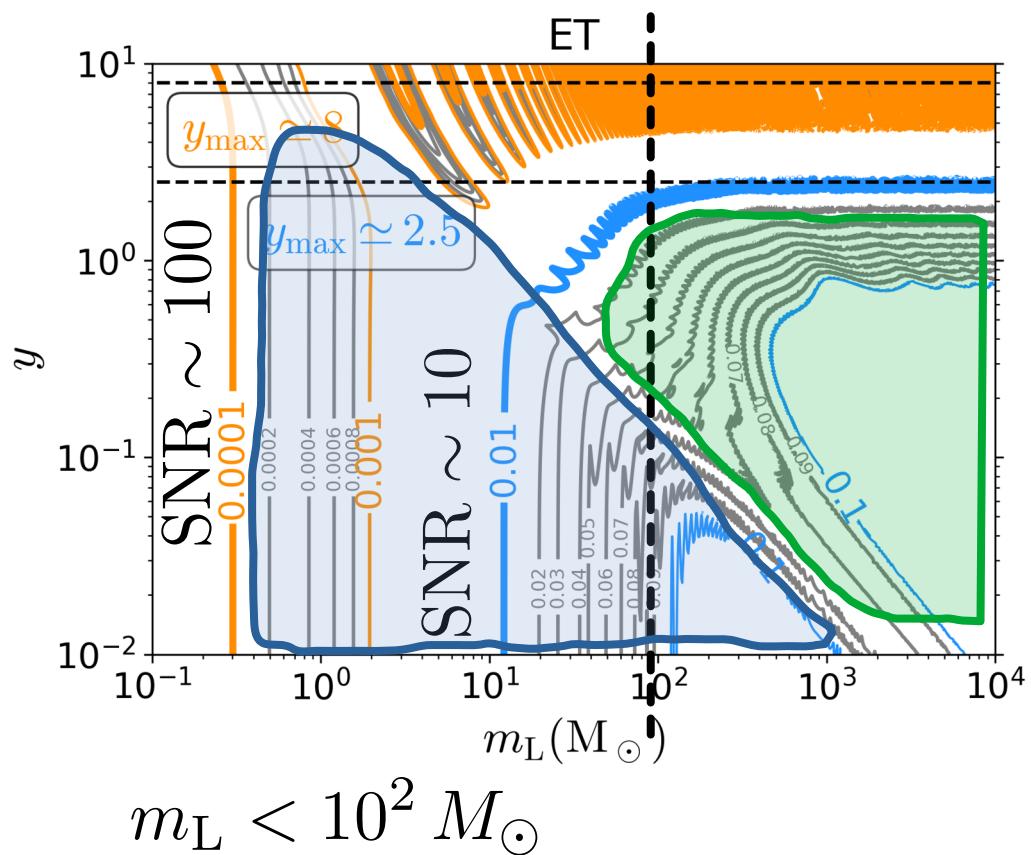
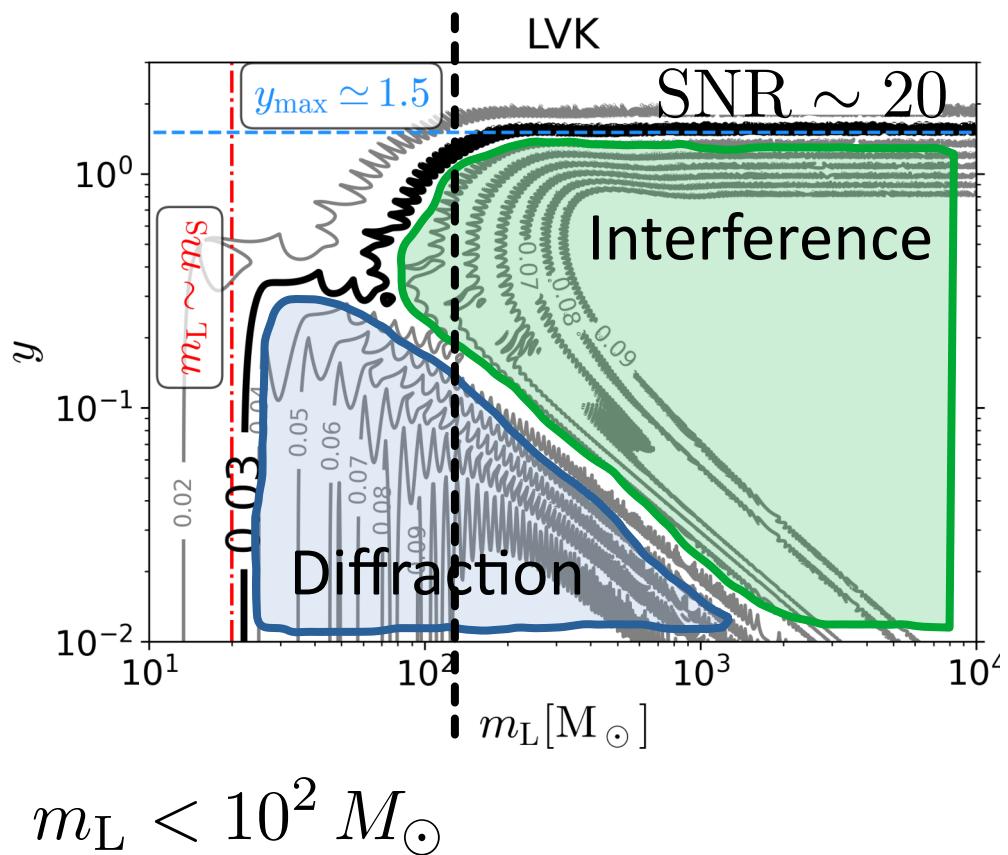


$$\begin{cases} m_L \gtrsim m_S \\ y < y_{max} \simeq 1.5 \end{cases}$$

$$y < y_{max} \simeq 2.5$$

Detectability

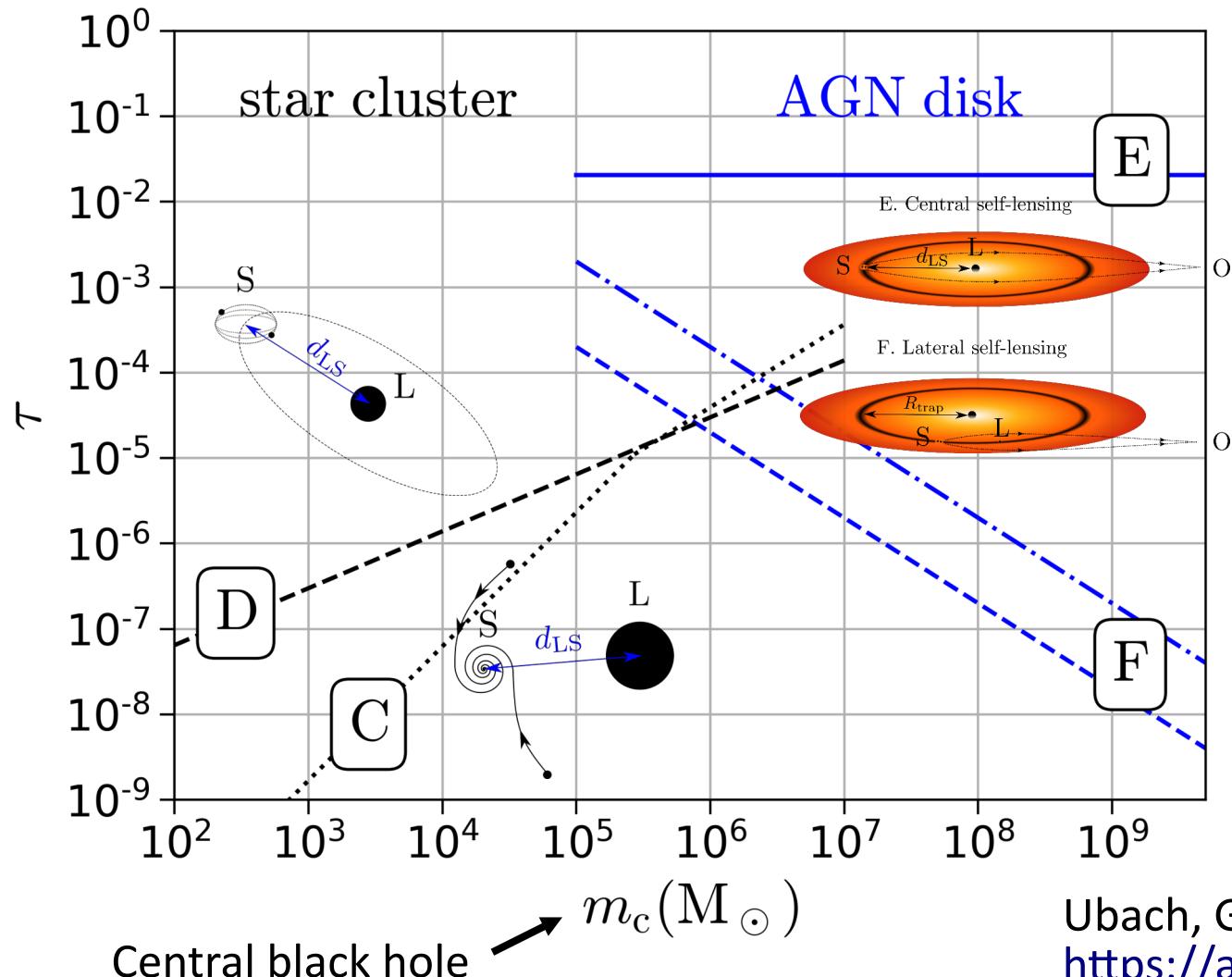
Stellar-mass BH lenses: mostly undetectable, $m_L \sim m_S$,



→ To have **detectable** imprint (interference pattern / multiple images), we need a **massive BH** in the star cluster (IMBH/SMBH)

Probability of self-lensing

- Probability of self-lensing (one lens): $\tau \propto \frac{v_{\text{orbit}}^2}{c^2} \propto \frac{R_L}{d_{\text{LS}}}$



Coincident with
Gondán&Kocsis (2022),
Leong et al. (2024)

$$y_{\max} = 1$$

Detectability

- Multiple images (strong lensing), $m_L \gtrsim 10^3 M_\odot$

$\text{SNR} > 8$ for both images

$$\left(\frac{\mu_+}{\mu_-}\right) = \left(\frac{\text{SNR}_{\text{lensed}}^+}{\text{SNR}_{\text{lensed}}^-}\right)^2 \rightarrow y_{\max}$$

For LVK, $(\text{SNR}_L^+)^{\max} = 50$, $y_{\max} \simeq 2$.

For ET, $(\text{SNR}_L^+)^{\max} = 1000$, $y_{\max} \simeq 10$.

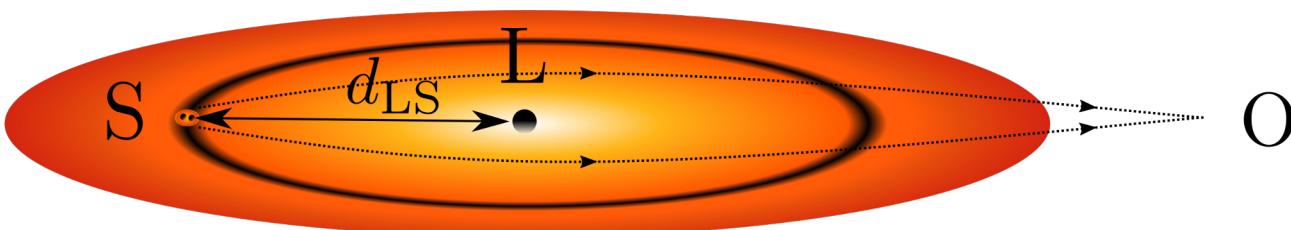
Signatures from environments

Detectable imprint: **interference pattern, multiple images**
→ central massive BH

- *How do we know if star cluster or AGN disk?*

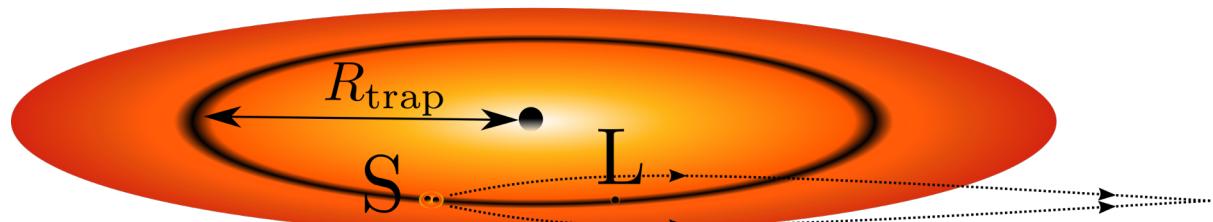
AGN disk has characteristic signature: h_+ **polarization**

E. Central self-lensing



Geometry:
edge-on disk
+ edge-on binary
(aligned with disk)

F. Lateral self-lensing

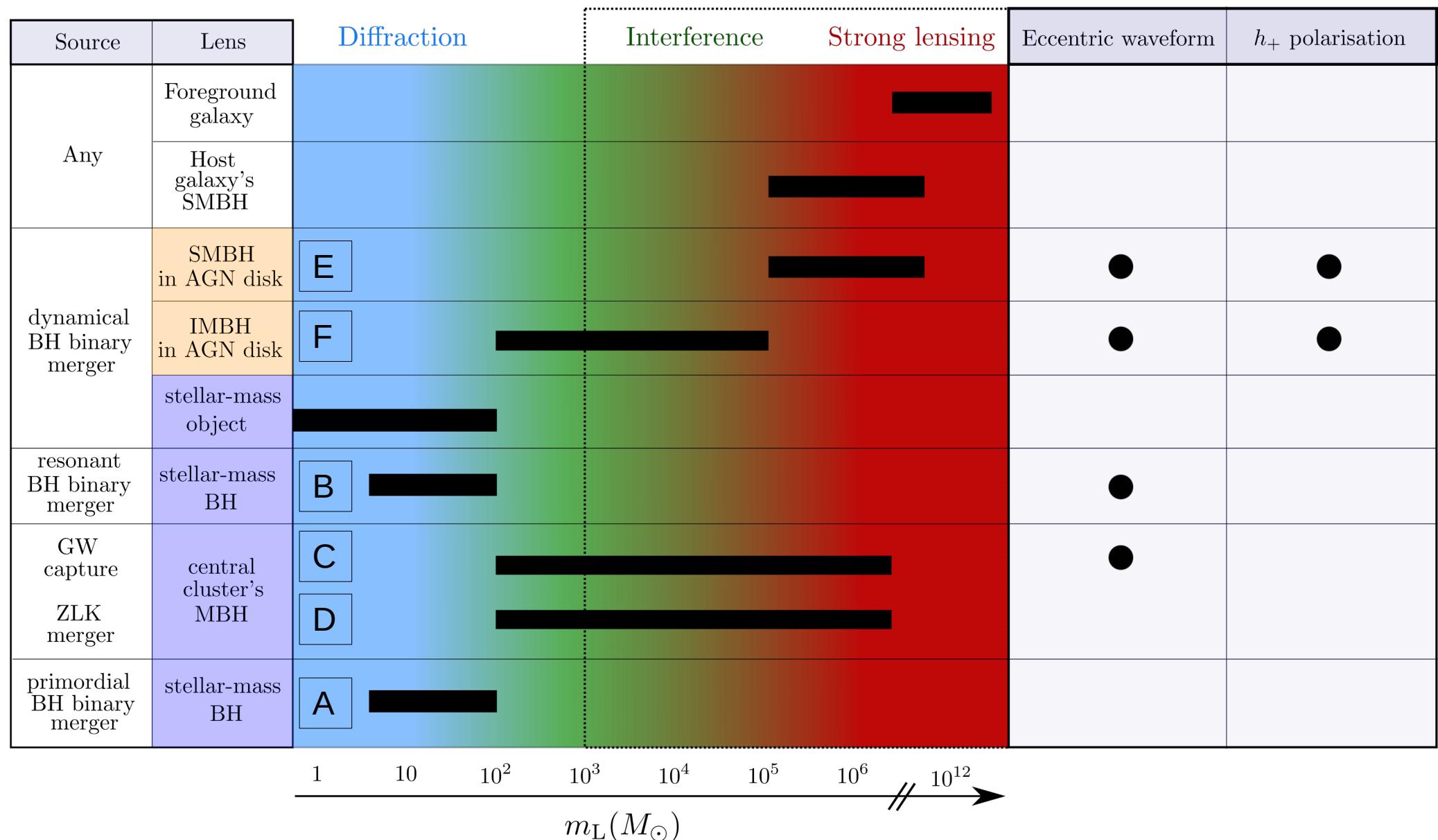


→ we receive
 h_+ polarisation

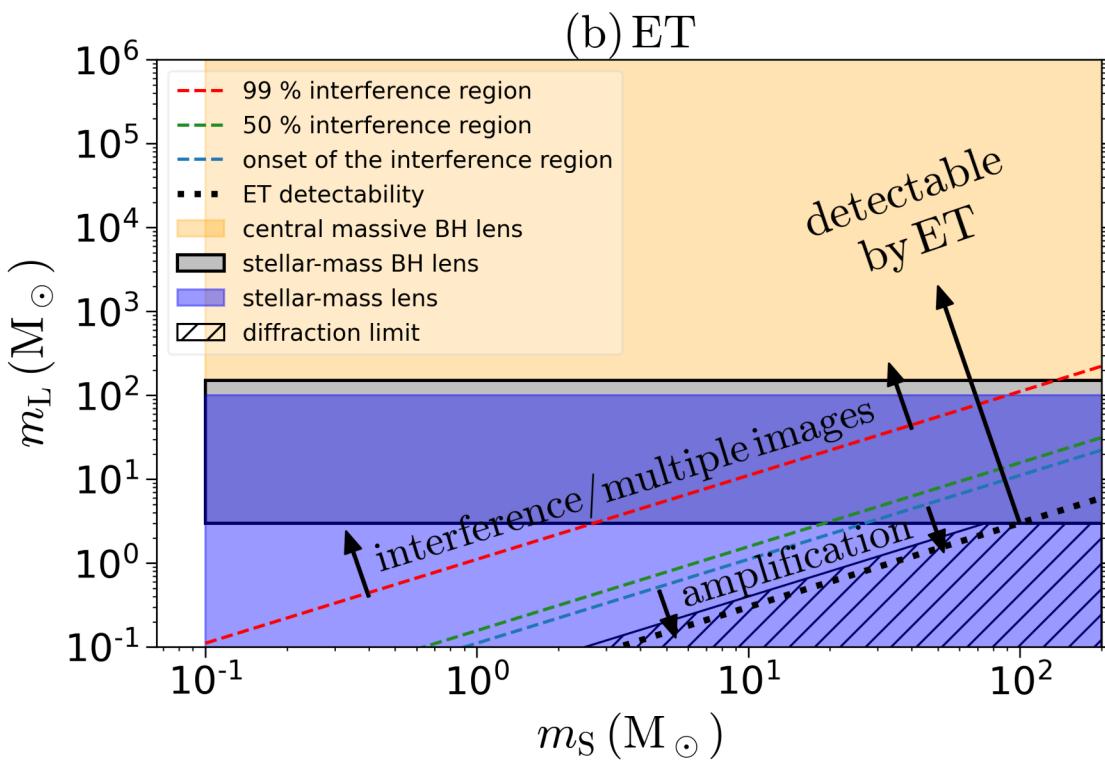
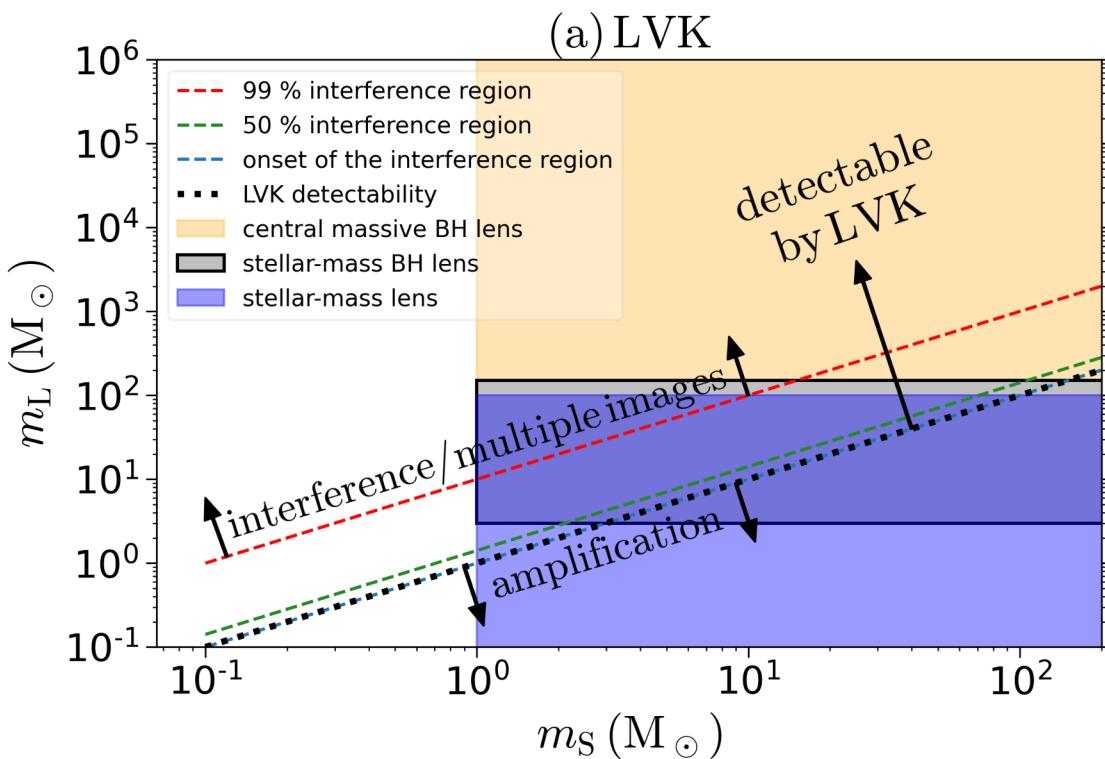
Conclusions

- Stellar-mass BH lenses are both unlikely and mostly undetectable (diffraction)
- AGN disk self-lensing has highest probability ($\tau \simeq 2 \times 10^{-2}$)
 - + detectable lensing imprint
 - + characteristic feature: h_+ polarization
→ could be distinguished from galaxy lensing, star cluster self-lensing
- Combining self-lensing with polarization and eccentricity can help constrain the astrophysical environment

Detectable imprint



Backup slides



Geometrical optics (GO) validity

GO approximation validity: $\nu \gtrsim \nu_G = \frac{1}{4y}$

Before:

$$\nu \gg 1$$



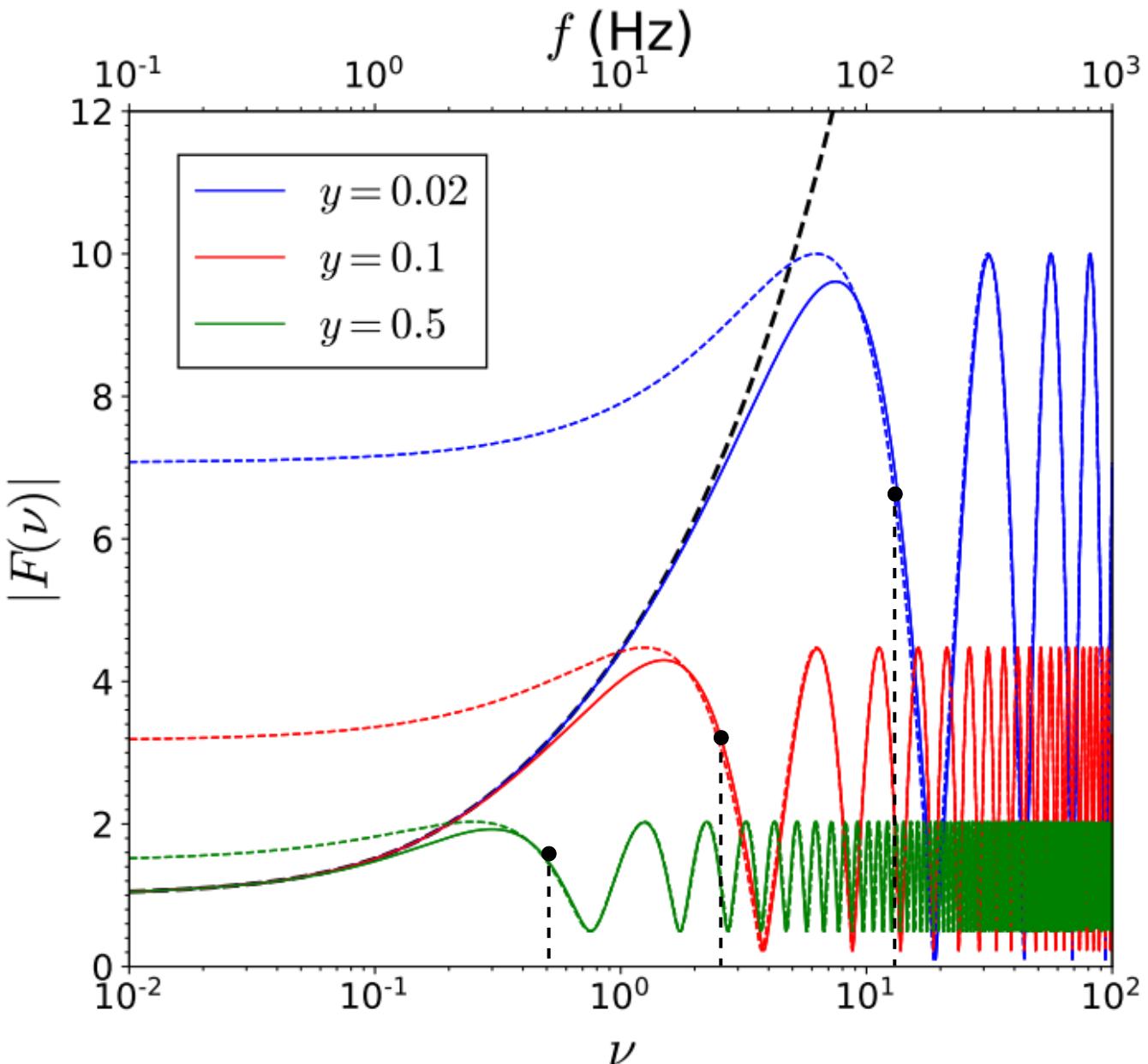
$$\lambda \cancel{\ll} R_S$$

$$R_S = \frac{2GM}{c^2}$$

$$\lambda \lesssim 8R_S y$$

- Less restrictive condition
- Depends also on y

Bulashenko and Ubach (2022)

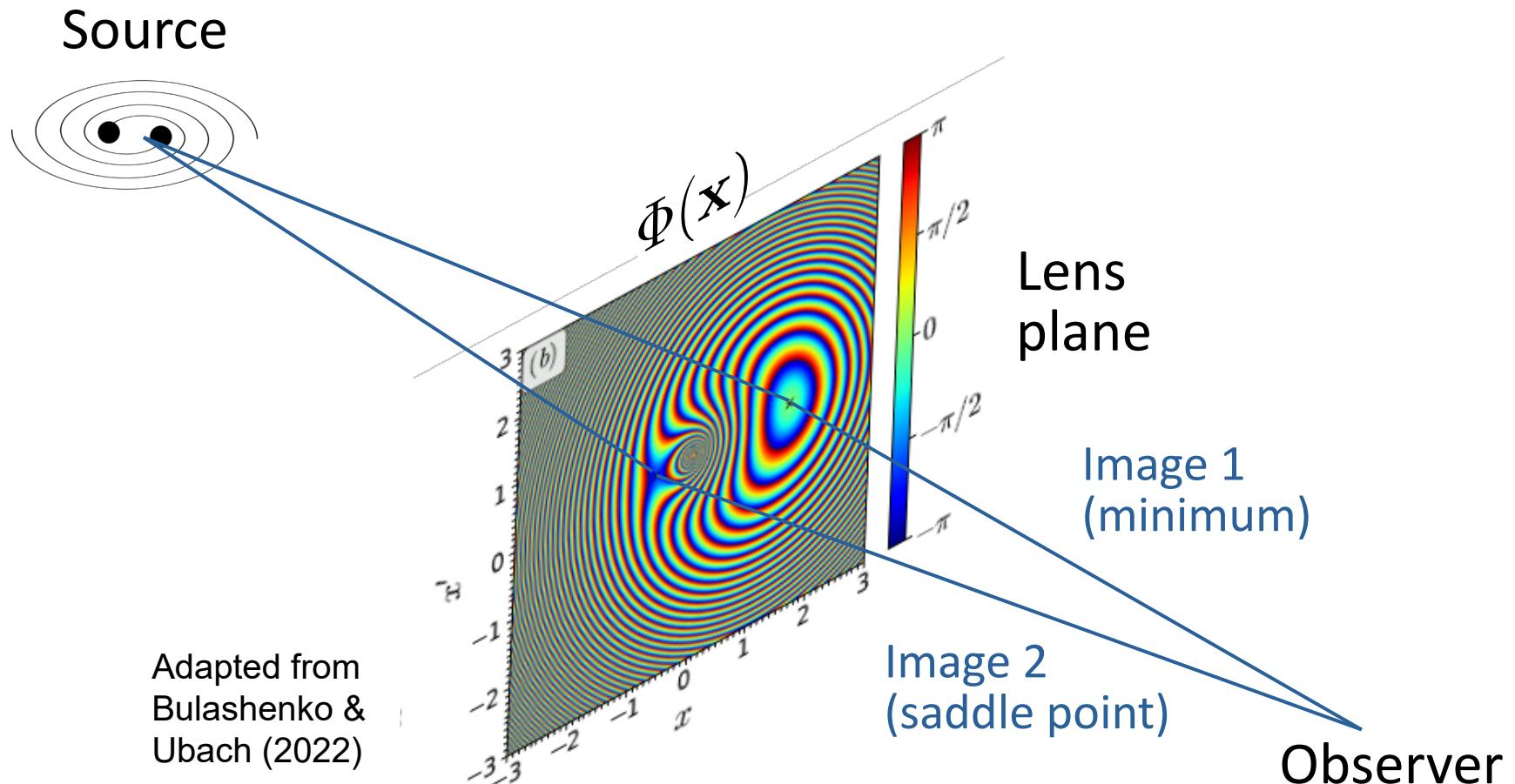


GO approximation
valid:

$$\nu \gtrsim \nu_G$$

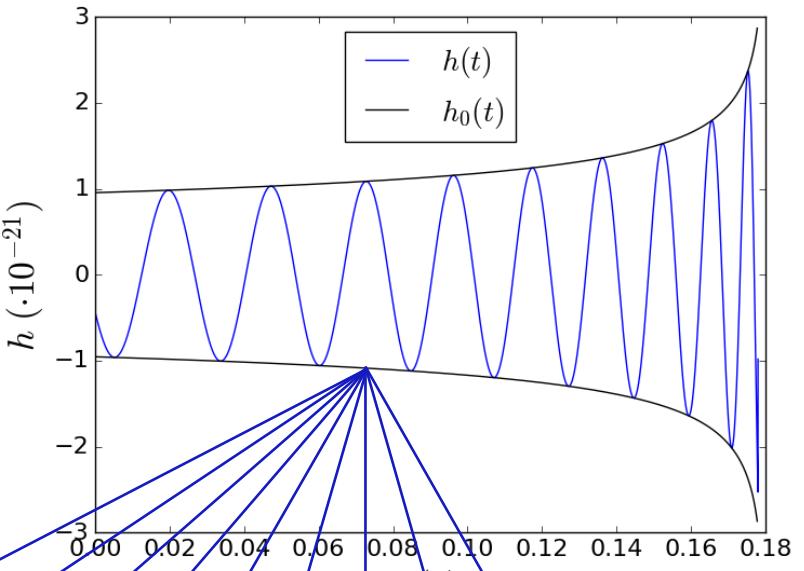
- $\nu_G = \frac{1}{4y}$

Wave effects



Detection: matched filtering

Template:



Recovery of an injected signal
(mock example)

